

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application.

Listing of Claims:

1. (Currently Amended) A Kalman-Viterbi joint channel equalizer, comprising:
 - a forward filter and a backward filter for receiving an input signal and a predetermined signal and performing filtering to the signals;
 - a Viterbi decoder for correcting errors during a transmission procedure in a blind mode;
 - a training symbol storing block for storing training symbols;
 - a switching block for classifying an output signal of the Viterbi decoder and symbols in accordance with a training mode and ~~a~~the blind mode, and inputting the output signal of the Viterbi decoder and symbols into the backward filter;
 - a Kalman gain calculating block for receiving input signals of the forward filter and the backward filter and calculating a Kalman gain;
 - an error signal calculating block for calculating an error signal by comparing an equalized signal, symbols, and the output signal of the Viterbi decoder with one another; and
 - a tap coefficient updating block for updating a tap coefficient of the filters by using the calculated error signal and the Kalman gain.
2. (Currently Amended) The Kalman-Viterbi joint channel equalizer according to claim 1, wherein the Kalman gain calculating block updates the tap coefficient by applying a fast Kalman algorithm in ~~a~~the blind mode.
3. (Currently Amended) The Kalman-Viterbi joint channel equalizer according to claim 2, wherein the Viterbi decoder uses a Viterbi decoding algorithm in the~~a~~ blind mode.
4. (Original) The Kalman-Viterbi joint channel equalizer according to any one of claims 1 to 3, wherein the Viterbi decoder reduces a tracing back length to use the reduced tracing back length in obtaining errors for tap coefficient updating.

5. (Original) The Kalman-Viterbi joint channel equalizer according to any one of claims 1 to 3, wherein the Viterbi decoder corrects errors by skipping symbols in a predetermined number of symbols to obtain errors for tap coefficient updating.
6. (Original) The Kalman-Viterbi joint channel equalizer according to any one of claims 1 to 3, wherein a symbol location of a robust stream is previously recognized and is applied to a data duration blind algorithm using the Viterbi decoder when an E-VSB is applied to the Kalman-Viterbi joint channel equalizer.
7. (Currently Amended) A VSB signal receiving system, comprising:
- a tuner for receiving an RF signal from an antenna and synchronizing the RF signal with a local oscillation signal to transform the RF signal into an IF signal;
 - an NTSC removing filter for removing an NTSC component from the IF signal to prevent degradation of an HDTV due to the NTSC component;
 - an equalizer for removing multi-path distortion generated in a transmission channel by equalizing the input signal;
 - a phase tracer for removing phase noise from the equalized signal;
 - a trellis decoder for performing trellis decoding with respect to an output signal of the phase tracer and outputting a decoded signal;
 - a data de-interleaver for performing reverse interleaving to the decoded signal;
 - an RS decoder for performing Reed-Solomon decoding to the output signal of the data de-interleaver so as to generate error-corrected bit streams; and
 - a de-randomizer for providing the output signal of the RS decoder to other elements of the VSB signal receiving system,
- wherein the equalizer further comprises:
- a forward filter and a backward filter for receiving an input signal and a predetermined signal and performing filtering to the signals;
 - a Viterbi decoder for correcting errors during a transmission procedure in a blind mode;
 - a training symbol storing block for storing training symbols;
 - a switching block for classifying the output signal of the Viterbi decoder and symbols in accordance with a training mode and ~~a~~the blind mode and inputting the output signal of the Viterbi decoder and symbols into the backward filter;

a Kalman gain calculating block for receiving input signals of the forward filter and the backward filter and calculating a Kalman gain;

an error signal calculating block for calculating an error signal by comparing an equalized signal, symbols, and the output signal of the Viterbi decoder with one another; and

a tap coefficient updating block for updating a tap coefficient of the filters by using the calculated error signal and the Kalman gain.